Accelerating Scilab Toolbox Creation using AI

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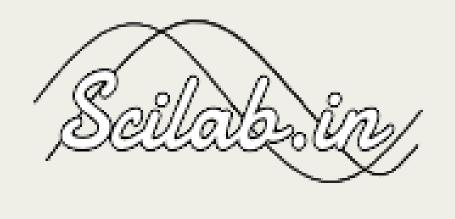
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About FOSSEE



- Free/ Libre Open Source Software for Education (FOSSEE)
- Funded by Ministry of Education, Government of India (MoE)
- Training and Skill based education
- Upskill students and faculty of academic institutions through FLOSS
- Recognize the contributors through Certificates, Honorarium and Online Recognition (URL), which have been used by students and teachers to get Internships, Jobs, or Scholarships for higher studies
- Promote FLOSS, thereby reducing the dependency on commercial software, thereby saving money
- Conducts various activities, Hackathons / Mapathons, Internships / Fellowships, Workshops

About Scilab



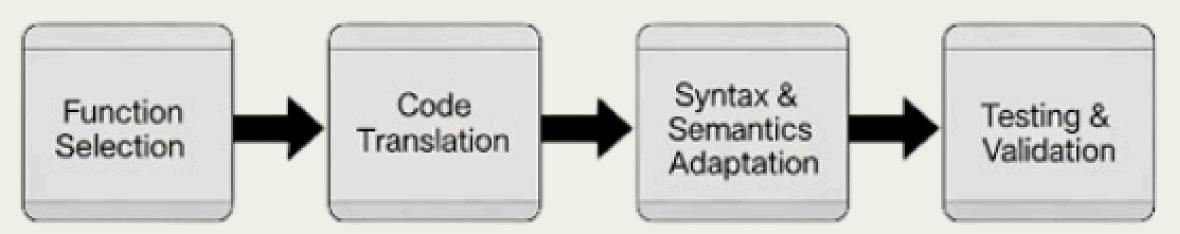
- Free and open source software
- Excellent computational environment
- A better solution to Matlab
- About 95% compatibility
- Xcos is a good alternative to simulink (Graphic modelling and simulation tool)
- To extend Scilab's capabilities toolboxes are also available

Motivation

- FOSSEE reached out to over 100 colleges and assisted them with Scilab through various activities.
- Scilab has a large user base with 100000+ downloads per month.
- However, Scilab lacks toolboxes in specific domains.
- Hence the toolbox development work initiated.

Methodology

- Function Selection: Identify relevant functions and scripts from the Octave Control Toolbox.
- Code Translation: Perform line-by-line mapping, replacing
 Octave functions with Scilab equivalents.
- Syntax & Semantics Adaptation: Adjust indexing, arguments, and plotting differences.
- Testing & Validation: Execute in both Octave and Scilab, compare outputs for accuracy.

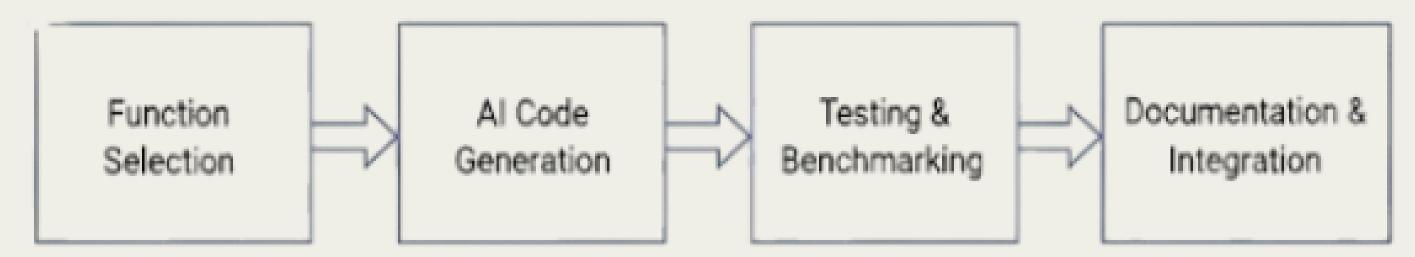


Challenges

- Manual translation from Octave/MATLAB to Scilab is slow and errorprone.
- Requires line-by-line understanding due to syntax and semantic differences.
- Missing Octave sub-functions in Scilab must be re-implemented.
- Default behavior mismatches (e.g., lyap) need compatibility fixes.
- Absence of SLICOT in Scilab forces manual handling of complex algorithms.
- Unsupported data types like iddata require redesign.
- Lack of test cases makes validation manual and difficult.

Toolbox Development Workflow using Al

- Function Selection: Map Octave functions to Scilab and note dependencies.
- Al Code Generation: Use LLMs to translate and suggest alternatives when no direct equivalent exists.
- Testing & Benchmarking: Run automated tests against Octave and refine iteratively.
- Documentation & Integration: Document validated functions with examples and add to the toolbox.



Implementation: mldivide

```
mldivide.m
File Edit Format Options Window Execute ?
                                                                               Edit View
mldivide.sci (C:\Users\Admin\Documents\mldivide.sci) - SciNotes
*mldivide.sci 💥
                                                                          ## Author: Lukas Reichlin <lukas.reichlin@gmail.com>
                                                                          ## Created: October 2009
                                                                          ## Version: 0.2
 1 function sys = mldivide(sys1, sys2)
    · · · · if · nargin() · ~= · 2 · then ·
                                                                          function sys = mldivide (sys1, sys2)
                                                                           if (nargin != 2) # prevent sys = mldivide (sys1, sys2, sys3, ...)
    ·····error("lti: mldivide: this is a binary operator")
                                                                              error ("lti: mldivide: this is a binary operator");
                                                                            endif
    \cdots end
                                                                            sys1 = inv (sys1); # let octave decide which inv() it uses
    \cdot \cdot \cdot \cdot \cdot sys1 \cdot = \cdot pinv(sys1);
                                                                            ## [p1, m1] = size (sys1);
    [p1, m1] = size(sys1);
                                                                            ## [p2, m2] = size (sys2);
    [p2, m2] = size(sys2);
                                                                            ## if (m1 != p2)
    ····/*if·p1·~=·m1·then
                                                                            ## error ("lti: mldivide: system dimensions incompatible: (%dx%d)
   ·····error("lti: mldivide: sys1 must be a square matri
                                                                          \\ (%dx%d)",
   x");
                                                                                        p1, m1, p2, m2);
10 ....end*/
                                                                            ## endif
11 \cdots if (m1 \cdot \sim = p2) then
                                                                            sys = sys1 * sys2;
                                                                          endfunction
12 · · · · · · error ("lti: · mldivide: · system · dimensions · incompatib
   lle");
13 · · · · else
15 --- end
16 endfunction
```

Implementation: mldivide

```
Scilab 2024.1.0 Console
                                                         Command Window
                                                                                                              X
File Edit Control Applications ?
                                                                                                            ⊞ ×
                                                        Command Window
Scilab 2024.1.0 Console
                                                              sys1 = [4, 3; 2, 1];
                                                              sys2 = [5; 6];
      sys1 = [4, 3; 2, 1];
                                                              sys = mldivide(sys1, sys2)
                                                        sys =
     sys2 = [5; 6];
                                                            6.5000
      sys = mldivide(sys1, sys2)
                                                          -7.0000
sys = [2x1 double]
   6.5
  -7.0000000
```

Functions Completed

Successfully completed 50 functions from Octave's Control System Toolbox.

append	uminus	mag2db	dsort	mrdivide
end_lti	uplus	gensig	pidstd	size_lti
parallel	db2mag	ctrb	strseq	dssdata
repsys	Boeing707	obsv	mpower	diff_iddata
times	covar_control	esort	mldivide	issiso

Functions Completed

isminmumphase	vertcat_iddata	iddata	cat_iddata	mktito
options	size_lti	acker	ssdata	augstate
isstable	nkshift_iddata	transpose	detrend_iddata	inv_ss
series	horzcat_iddata	pole	fft_iddata	ctranspose
thiran	merge_iddata	get_iddata	ifft_iddata	issiso

Documentation

The documentation part typically includes four key parts:

- Syntax: The order in which the function evaluates its parameters.
- Parameters: Details about the expected inputs, including their types and valid ranges.
- Description: An in-depth explanation of the function's behavior, including default settings, input-output expectations, dependencies, and other relevant information.
- Examples: Sample usage illustrating how the function should be used correctly.

Future Scope

- Complete the remaining functions of the Control System
 Toolbox
- Leverage AI to develop additional Scilab toolboxes
- Enhance and optimize existing toolboxes
- Improve user documentation and add more demos for a better user experience

Acknowldgement

- We thank the FOSSEE Team at IIT Bombay for the internship opportunity on Scilab Control Toolbox development.
- Our gratitude goes to Prof. Kannan Moudgalya for his support and guidance.
- This project was part of the FOSSEE Semester-long internship.
- Thanks to Ms. Rashmi Patankar, Project Manager at FOSSEE IITB, Ms. Vineeta Parmar, Senior Project Manager at FOSSEE IITB and the Scilab team for their mentorship.
- We appreciate the Department of Electronics and Communication Engineering at **PSG College of Technology** for providing a strong foundation.
- Special thanks to **Dr. Krishaveni V, Head of ECE at PSG College of Technology,** for inspiring participation in this open-source initiative.

Thank you!

QUESTIONS?

Contact us at

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